

July 14, 2004

DECLARATION

The undersigned, Dana Scruggs, having an office at 8902B Otis Avenue, Suite 204B, Indianapolis, Indiana 46216, hereby states that she is well acquainted with both the English and German languages and that the attached is a true translation to the best of her knowledge and ability of PCT/DE 03/01080 (INV.: SKULTETY-BETZ, U., ET AL), entitled "Distance Measuring Device".

The undersigned further declares that the above statement is true; and further, that this statement was made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or document or any patent resulting therefrom.

A handwritten signature in cursive script that reads "Dana Scruggs".

Dana Scruggs

5/6
D

1 DISTANCE MEASURING DEVICE

2

3 Background Information

4

5 The present invention is directed to a distance measuring device according to the
6 definition of the species in Claim 1.

7

8 Laser distance measuring devices are known that determine the distance to a
9 target object using a laser. In determining the horizontal distance, the laser beam
10 must be oriented as exactly horizontally as possible to prevent measurement
11 errors.

12

13 To this end, known laser distance measuring devices include "bubble tubes", via
14 which the operator can recognize the tilt of the distance measuring device
15 relative to the horizontal line.

16

17 With this type of orientation of the laser measuring device, the operator must
18 therefore simultaneously set his sights on the target object to be measured and
19 look at the bubble tube, which is difficult with handheld distance measuring
20 devices in particular.

21

22 Furthermore, laser distance measuring devices are known, with which the tilt of
23 the laser distance measuring device is determined using an integrated tilt sensor,
24 to subsequently correct the measured distance based on trigonometric
25 relationships.

26

27 Advantages of the Invention

28

29 The present invention includes the general technical teaching that the distance
30 measuring device has a position sensor that detects the spacial orientation of the
31 distance measuring device, whereby the position sensor is connected with a

1 signal transducer that emits a perceptible signal that is a function of the spacial
2 orientation of the distance measuring device.

3

4 The operator can therefore concentrate on setting his sights on the target object
5 when operating the distance measuring device and is thereby informed via the
6 signal transducer about the spacial orientation of the distance measuring device.

7

8 The signal transducer can be, e.g., an optical signal transducer, an acoustic
9 signal transducer and/or a tactile signal transducer. The present invention is not
10 limited to these types of signal transducers, however. The only decisive point is
11 that the signal emitted by the signal transducer be perceptible by the operator
12 and contain information about the spacial orientation of the distance measuring
13 device.

14

15 In the preferred embodiment of the invention, the signal transducer is an optical
16 signal transducer, however, which is capable of being triggered by the position
17 sensor to emit an optical signal, whereby the intensity, color, brightness, blinking
18 frequency and/or blinking duration are a function of the spacial orientation of the
19 distance measuring device. For example, the blinking frequency can be
20 increased as the orientation of the distance measuring device approaches the
21 horizontal line, until the optical signal transducer finally remains illuminated when
22 the distance measuring device is oriented approximately horizontally. It is also
23 possible as an alternative, however, that, given a constant blinking frequency, the
24 duration of the individual blinking pulses is changed when there is a deviation
25 from the horizontal line.

26

27 The optical signal transducer is preferably the laser that is also used for distance
28 measurement. This offers the advantage that a separate signal transducer can
29 be eliminated, which enables economical fabrication.

30

1 In another variant of the present invention, an acoustic signal transducer is used
2 as the signal transducer, which emits an acoustic signal which is a function of the
3 spacial orientation of the distance measuring device. A conventional loudspeaker
4 can be used for this purpose, for example, although other electro-acoustic
5 converters are also usable.

6

7 The signal emitted by the acoustic signal transducer can be changed, e.g., as a
8 function of the spacial orientation of the distance measuring device, in terms of
9 its pitch and/or tonal frequency, volume, frequency and/or duration of recurrence
10 to inform the operator about the spacial orientation of the distance measuring
11 device. For example, the acoustic signal transducer can emit beep tones at
12 specified intervals, whereby the interval duration becomes shorter as the
13 distance measuring device approaches the horizontal line, until the acoustic
14 signal transducer finally emits a steady beep tone when the distance measuring
15 device is located approximately in the horizontal line.

16

17 Further, it is also possible that the signal transducer is a tactile signal transducer
18 that emits to the operator a perceptible tactile signal which is a function of the
19 spacial orientation of the distance measuring device. For example, with handheld
20 distance measuring devices, an electro-mechanical actuator can be installed in a
21 handle of the distance measuring device, which transmits a tactile signal to the
22 operator's hand. The tactile signal can be a series of pressure pulses, for
23 example, whereby the interval duration between the individual pressure pulses is
24 varied as a function of the spacial orientation of the distance measuring device.
25 For example, the interval duration can be reduced as the distance measuring
26 device approaches the horizontal line. It is also possible, however, that a
27 vibration generator is used as tactile signal transducer, which generates a
28 vibration signal as long as the distance measuring device is not oriented
29 correctly.

30

1 In the preferred embodiment of the invention, the position sensor is a tilt sensor
2 that measures the angle of tilt of the distance measuring device. The tilt sensor is
3 preferably situated such that the measured angle of tilt is equal to the angle
4 between the laser beam and the horizontal or vertical lines.

5

6 It is also possible as an alternative, however, that the position sensor does not
7 measure the elevation angle, but rather the angle in a horizontal line. This can be
8 advantageous, for example, when various target objects which lie in a horizontal
9 line and should form a specified angle are sighted in sequence, so that
10 trigonometric calculations can be carried out subsequently with reference to the
11 measured results. The position sensor can contain a compass, for example,
12 which makes a corresponding angular measurement possible.

13

14 The measured elevation or azimuth angles are preferably compared with a
15 specified setpoint value. In the example of a horizontal distance measurement
16 described initially, this setpoint value typically corresponds to the horizontal line
17 with an elevation angle of zero degrees. With a vertical height measurement, on
18 the other hand, the setpoint value typically corresponds to an elevation angle of
19 90 degrees.

20

21 In an advantageous variant of the invention, the distance measuring device
22 enables a horizontal distance measurement and a vertical height measurement
23 by adjusting the particular setpoint value accordingly. This adjustment of the
24 setpoint value for the angle of tilt can take place manually by the operator, for
25 example, by the operator entering the desired operating mode via an input device
26 of the distance measuring device.

27

28 In a variant of the invention it is provided, on the other hand, that the distance
29 measuring device adjusts the setpoint angle automatically. For example, the
30 setpoint angle can be set to zero degrees in accordance with the horizontal line
31 when the currently measured elevation angle is between –30 degrees and +30

1 degrees. The setpoint angle, on the other hand, is set to 90 degrees in
2 accordance with the vertical line when the currently measured elevation angle is
3 between +60 degrees and +120 degrees. In this variant of the invention, the
4 operator need therefore only orient the distance measuring device roughly
5 horizontally or vertically, and the associated setpoint value is automatically set.

6

7 Drawing

8

9 Further advantages result from the following description of the drawing. An
10 exemplary embodiment of the invention is presented in the drawing. The
11 drawing, description, and claims contain numerous features in combination. One
12 skilled in the art will advantageously consider them individually as well and
13 combine them into reasonable further combinations.

14

15 Figures 1 shows a perspective depiction of a laser distance measuring device
16 according to the invention,
17 Figure 2 shows a simplified block diagram of the laser distance measuring
18 device from Figure 1,
19 Figure 3 shows a block diagram of an alternative laser distance measuring
20 device with a loudspeaker,
21 Figure 4 shows a block diagram of an alternative laser distance measuring
22 device with a signal lamp, and
23 Figure 5 shows a block diagram of an alternative laser distance measuring
24 device with a tactile signal transducer.

25

26 Detailed Description of the Embodiments

27

28 The perspective depiction in Figure 1 shows a handheld laser distance
29 measuring device 10 that makes it possible to carry out a precise distance
30 measurement without a stand. To this end, laser distance measuring device 10
31 emits a laser beam at its front side in a conventional manner, the laser beam

1 being directed at the target object to be measured and being reflected off of it.
2 The distance to the target object to be measured can be calculated based on the
3 propagation time from the time the laser beam is emitted by laser distance
4 measuring device 10 until it is received.

5

6 To this end, laser distance measuring device 10 has an integrated laser 12 that is
7 controlled by a control unit 14.

8

9 To receive the laser beam reflected on the target object, laser distance
10 measuring device 10 further includes an optical sensor which is also connected
11 with control unit 14, so that control unit 14 calculates the distance to the target
12 object to be measured and emits a corresponding distance signal d to a display
13 18 which is located on the top side of laser distance measuring device 10.

14

15 Laser distance measuring device 10 is operated using a keypad 20, which is also
16 located on the top side of laser distance measuring device 10.

17

18 The unique feature of laser distance measuring device 10 is the fact that, with it,
19 spacial orientation during the measurement procedure is simplified. For example,
20 laser distance measuring device 10 must be oriented as exactly horizontally as
21 possible during a horizontal distance measurement, or measurement errors will
22 occur. Accordingly, laser distance measuring device 10 must be oriented as
23 exactly vertically as possible during a vertical height measurement to achieve a
24 high level of measurement accuracy.

25

26 Laser distance measuring device 10 therefore includes an integrated tilt sensor
27 22 that measures the tilt of laser distance measuring device 10 and emits a
28 corresponding angle of tilt α . Tilt sensor 22 is located in laser distance measuring
29 device 10 in such a manner that angle of tilt α indicates the angle formed by the
30 laser beam relative to the horizontal line.

31

1 On the output side, tilt sensor 22 is connected with a comparator unit 24 that
2 compares the measured angle of tilt α with a specified setpoint angle α_{SOLL} which
3 the operator can enter or select on keypad 20. To carry out a horizontal distance
4 measurement, the operator then enters a setpoint angle of $\alpha_{SOLL} = 0^\circ$ on keypad
5 20, which corresponds to the horizontal line. To carry out a vertical height
6 measurement, the operator then enters a setpoint angle of $\alpha_{SOLL} = 0^\circ$ on keypad
7 20, which corresponds to the vertical line.

8

9 Comparator unit 24 emits an angle of error $\Delta\alpha = \alpha - \alpha_{SOLL}$ on the output side that
10 indicates the deviation of the current spacial orientation of laser distance
11 measuring device 10 from the desired spacial orientation.

12

13 Angle of error $\Delta\alpha$ is then supplied to a control unit 26 that calculates a blinking
14 frequency f as a function of angle of error $\Delta\alpha$, whereby blinking frequency f
15 decreases as angle of error $\Delta\alpha$ decreases.

16

17 Blinking frequency f , which is determined by control unit 26, is then supplied to
18 control unit 14, whereby control unit 14 controls laser 12 such that the emitted
19 laser beam blinks with blinking frequency f . Based on blinking frequency f of laser
20 12, the operator can then determine if laser distance measuring device 10 is
21 oriented correctly. In so doing, the operator need only move laser distance
22 measuring device 10 such that the blinking becomes faster, until laser 12 finally
23 beams constantly when laser distance measuring device 10 is oriented in
24 accordance with the specified angle α_{SOLL} , and the actual distance measurement
25 can therefore be carried out.

26

27 The exemplary embodiment depicted in Figure 3 largely conforms with the
28 exemplary embodiment described herein above and depicted in Figures 1 and 2,
29 so the same reference numerals will be used herein below for corresponding
30 components, and the above description will be referred to, to avoid repetition.

1 A unique feature of this exemplary embodiment is that, to support the operator in
2 the spacial orientation of laser distance measuring device 10, a loudspeaker 28
3 is provided that is controlled by a control unit 26' having a variable frequency f.
4 Control unit 26' determines frequency f as a function of angle of error $\Delta\alpha$,
5 whereby frequency f decreases as angle of error $\Delta\alpha$ decreases.

6

7 In a horizontal distance measurement, the pitch of the signal emitted by
8 loudspeaker 28 therefore increases the more closely the horizontal line is
9 approached, so that the operator can correctly orient laser distance measuring
10 device 10 in a simple manner.

11

12 In a vertical distance measurement, the pitch of the signal emitted by
13 loudspeaker 28 increases accordingly the more closely the vertical line is
14 approached.

15

16 The exemplary embodiment depicted in Figure 4 also largely conforms with the
17 exemplary embodiment described herein above and depicted in Figures 1 and 2,
18 so the same reference numerals will be used herein below for corresponding
19 components, and the above description will be referred to, to avoid repetition.

20

21 The unique feature of this exemplary embodiment is that a signal lamp 30 is
22 provided to signal the spacial orientation of laser distance measuring device 10,
23 whereby signal lamp 30 is positioned on laser distance measuring device 10
24 such that the operator sees signal lamp 30 when sighting the target object. This
25 positioning of signal lamp 30 is advantageous because, in this manner, the
26 operator can simultaneously sight the target object and check the spacial
27 orientation of laser distance measuring device 10.

28

29 Signal lamp 30 is controlled by a control unit 26" with a blinking frequency f ,
30 whereby blinking frequency f increases as laser distance measuring device 10

1 approaches the desired setpoint angle α_{SOLL} . Signal lamp 30 therefore blinks that
2 much faster the more exactly laser distance measuring device 10 is oriented.

3

4 The exemplary embodiment depicted in Figure 4 also largely conforms with the
5 exemplary embodiment described herein above and depicted in Figures 1 and 2,
6 so the same reference numerals will be used herein below for corresponding
7 components, and the above description will be referred to, to avoid repetition.

8

9 The unique feature of this exemplary embodiment is that, to signal the spacial
10 orientation of laser distance measuring device 10, a tactile signal transducer 32
11 is provided that emits a tactile signal to the operator, who is holding laser
12 distance measuring device 10 in his hand. Tactile signal transducer 32 emits
13 short pressure pulses with a specified frequency of recurrence f to the operator,
14 whereby the frequency of recurrence f is a function of angle of error $\Delta\alpha$ and is
15 calculated by a control unit 26".

16

17 As the spacial orientation of laser distance measuring device 10 approaches the
18 desired orientation, frequency of recurrence f increases, based on which the
19 operator can check the spacial orientation of laser distance measuring device 10.

20

21 The design of invention is not limited to the preferred exemplary embodiments
22 indicated herein above. Rather, a number of variants are feasible which make
23 use of the means of attaining the invention that were presented, even with
24 fundamentally different types of designs.

1 Reference Numerals

2

10	Laser distance measuring device
12	Laser
14	Control unit
16	Optical sensor
18	Display
20	Keypad
22	Tilt sensor
24	Comparator unit
26, 26', 26'', 26'''	Control unit
28	Loudspeaker
30	Signal lamp
32	Tactile signal transducer

3

4